

# INVT BPD BASIC SETUP MANUAL







# PRODUCT PACKAGING INCLUDE





## SWITCH BOX INCLUDE



LED keypad display, LED display cable, communication port, communication port cable, and Hand, off, Auto switch,



# **PRODUCT SPECIFICATIONS**



Model	BPD0K7 TN(AC)	BPD1K5 TN(AC)	BPD2K2 TN(AC)	BPD004 TNAC	BPD2K2 TRAC(S)	BPD004 TRAC(S)	BPD5K5 TRAC(S)
			DC input	ł			
Maximum DC voltage (V)		45	0			800	
Starting voltage (V)	80		100		220		
Minimum working voltage (V)	60		80			180	
Recommended MPPT voltage (V)	80–400		100–400			220–750	
Number of input channels	1/MC4 connector	2/	MC4 connect	or	1/MC4 connector	2/MC4 c	onnector
Maximum input DC current (A)	9	12	12	20	12	20	20
		Bypass AC	input (suppor	ting mains in	iput)		
Input voltage (V AC)	220	)/230/240(1PH	l) (-15%–+10%	6)	380 (	3PH) (-15%–+	10% <b>)</b>
Input frequency (Hz)				47–63			
AC input terminal		L, N,	PE			R, S, T, PE	
			AC outpu	it			
Rated power (W)	750	1500	2200	4000	2200	4000	5500
Rated current (A)	5.1 (1PH) 4.2 (3PH)	10.2 (1PH) 7.5 (3PH)	14 (1PH) 10 (3PH)	25 (1PH) 16 (3PH)	5.5	9.5	14
Output voltage (V AC)			0.	-Input voltage			
Output wiring mode Output frequency	control 3P3L: Connecte motor	Connected to a 3PH asynchronous     motor			asynchronous		
(Hz)				1-400			
Control modo	r	C	ontrol perfor	mance			
Motor type	A	unchronous m	otor (1DU/2DL	V/F	Async	aronous motor	· (2DLI)
	A5	ynchionous m	Other naram	i) eters	Asylici		(3F11)
Dimensions	255×300			410×360	331×360		
(WxDxH) (mm)	×137	280×30	00×137	×154.5	×154.5	454×36	0×154.5
Net weight (kg)	6.4	1	7	13.15	10.1	14	.1
Package weight (kg)	8.5	ç	9	16	12	1	6
Ingress protection rating				IP65	-		
Cooling			N	latural cooling			
HMI	External LED keypad						
	Communication terminals						
External communication	RS485/3 digital inputs						
Communication interface			Multi-core	waterproof co	onnector		
			Certificati	on			
Standards		CE; E	MC meets the	requirements	of IEC61800-3	3 C3.	
		Op	perating envir	onment			
Ambient		-25–6	0°C (derated a	at temperature	higher than 4	5°C)	
Altitude		300	0 m (derated a	at altitude hidr	her than 2000 r	m)	
7 111000							

# **KEYPAD INTRODUCTION**



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No.	Name	Description		
		RUN,	/TUNE	Running status indicator. LED off means that inverter is in the stopping state; LED blinking means the inverter is in the parameter auto tuning sate; LED on means the inverter is in the running state.
1	Status	FWE	)/REV	FED/REV indicator. LED off means the inverter is in the forward rotation state; LED on means the inverter in in the reverse rotation state.
	indicator	LOCAL/	REMOTE	LED for keypad operation, terminals operation and remote communication control; LED off means that the inverter is in the keypad operation state; LED blinking means the inverter is in the remote communication control state.
		TI	RIP	Fault indicator. LED on when the inverter is in the fault state; LED off in normal state; LED blinking means the inverter is in the overload pre-alarm state.
2	Unit Indicator	Indicating the unit of the displayed digits		Hz – Unit of frequency A – Unit of current V – Unit of voltage RPM – Unit of rotating speed % – Percentage
3	Code displaying zone	displaying zone		5-digit LED display , displaying various monitoring data and alarm code such as set frequency and output frequency
4	Analog potentiomet er	Corresponds to Al	1.	
		PRG ESC	Programming key	Enter or escape from the first level menu and remove the parameter quickly
		DATA ENT	Entry key	Enter the menu step-by-step confirm parameters
5 Buttons			Up key	Increase data or function code progressively
	Buttons	V	Down key	Decrease data or function code progressively
		<mark>≫</mark> SHIFT	Right-shift key	Move right to select the displaying parameter circularly in stopping and running mode. Select the parameter modifying digit during the parameter modification.
		♦RUN	Run key	This key is used to run the inverter in key operation mode.
	STOP RST	Stop /Reset key	This key is used to stop the inverter when it is in running state, and is limited by function code PO07.04 This key is used to reset all control modes in	

# BASIC SETUP 230V 3PH / 380V 3PH

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#### NB: Pump need to be off to set box

GROUP 0	BASIC FUNTION GROUP				
00.01	1	Terminal Run Command			
00.03	50	Maximum Running Frequency			
00.04	50	Upper Freq Limit			
00.05	35	Minimum Running Frequency			
00.11	1.5	Acceleration time	1.5 Borehole 20 Centrifugal		
00.12	15	Deceleration time	15 Borehole 20 Centrifugal		
00.13	0/1	Rrunning direction			
GROUP 1	START UP AND S	TOP CONTROL			
1.08	0	Stop mode			
01.18	1	Operation protection			
01.21	1	Restart after power of			
GROUP 2	MOTOR 1 PARA	MMETER			
02.00	0	Motor type	0=3PH Motor, 1=1PH Motor		
02.01		Rated of Power (kW)	TO BE OBTAINED FROM MOTOR		
02.02	50	Rated of Freq (Hz)			
02.03		Rated of Speed (RPM)	TO BE OBTAINED FROM MOTOR		
02.04	230 / 380	Rated of Voltage (V)	TO BE OBTAINED FROM MOTOR		
02.05		Rated Current (A)	TO BE OBTAINED FROM MOTOR		
GROUP 4	SVPWM CONTRO	DL			
04.34	10	2PH control of 1Ph Motor	10=3PH Motor or with cap, 01=1PH Motor		
GROUP 5	Input terminals				
05.01	0	S1 Terminals function selection			
05.02	1	S2 Terminals function selection	Fw Run		
05.03	46	S3 Terminals function selection	46 = No Water Signal (Probes) 0 = No Function		
05.10	4	HDI Terminals Function	s3 polarity switch		
GROUP 8	ENHANCED FUN	CTIONS	-		
08.28	8	Nr. Fault Reset Times			
08.29	1000	Fault reset seconds			
GROUP 11	PROTECTIVE PAI	RAMETERS			
11.06		Auto current limit	Default 120		
11.09		Overload protection	Default 120		
GROUP 15	GROUP SPECIAL	FUNCTION PARAMETERS FOR PV INVERT	ER		
15.00	1	PV inverter selection			
15.01	1	Vmpp Voltage reference			
15.05	70%	Lower freq limit %	See setting below		
15.20	100	Delay Time Weak Light	ALS detection time		
15.21	600	Wake-up delay weak Light			
15.29	2	PV /AC INPUT SELECTION	0=Auto, 1=AC, 2=PV		
15.32	5	Empty-water delay	A-TL detection time		
15.33	1200	Wake-up delay empty-water	A-TL wake up time		
Setting		Setting			
15.05 = P00.05 / P00.03*100 11.06 = Motor Amp / Rated output current of drive *100					

11.09 = 11.06 + 3

All setting in yellow to be set



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04.34	01	2PH control of 1Ph Motor	10=3PH Motor or with cap, 01=1PH Motor	
04.35		Phase Balancing	See advance setting page	
GROUP 5	Input terminals			
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GROUP 11	PROTECTIVE PAP	RAMETERS		
11.06		Auto current limit	Default 120	
11.09		Overload protection	Default 120	
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GROUP 15	GROUP SPECIAL	FUNCTION PARAMETERS FOR PV INVERT	ER	
15.00	1	PV inverter selection		
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Setting		Setting		
15.05 = P00.05 / P00.03*100 11.06 = Motor Amp / Rated output current of drive *100				

11.09 = 11.06 + 3

All setting in yellow to be set



# Auto AC / DC Setup

GROUP 15	GROUP SPECIAL FUNCTION PARAMETERS FOR PV INVERTER				
15.29	0	PV /AC INPUT SELECTION	0=Auto, 1=AC, 2=PV		
15.30	230	Threshold setting for switching to AC			
15.31	230	Threshold setting for switching to PV			

## **Dry Run Settings**

GROUP 15	GROUP SPECIAL FUNCTION PARAMETERS FOR PV INVERTER			
15.17	50	Current detection of underload	See setting below (Default 50)	

Setting = Drive current / motor current at 30Hz x 100

Drive Rated Current

MODEL	BPDOK7	BPD1K5	BPD2K2	BPD4K0	BPD2K2	BPD4K4	BPD5K5
	TN	TN	TN	TN	TRAC	TRAC	TRAC
Rated current (A)	5.1 (1PH) 4.2 (3PH)	10.2 (1PH) 7.5 (3PH)	14 (1PH) 10 (3PH)	25 (1PH) 16 (3PH)	5.5	9.5	14

## Phase Balancing of 04.35 for 230V 1PH (Excl Run Cap)

GROUP 4	SVPWM CONTROL		
04.35		Phase Balancing	See advance setting below

Phase Balancing:

Check value of 17.38 and 17.39 while inverter is running at 50 Hz. The goal is to get these figures as close as possible

To accomplish this, adjust 04.35 from 0.75 to 1.25 and constantly monitor 17.38 and 17.39 after each adjustment (Adjustment tolerance of 04.35 +/- 0.2)

## **Reset Drive**

#### Factory Default Reset:

GROUP 0	BASIC FUNTION GROUP				
00.18	1	Factory Default Drive	0 = No operation, 1 = Restore the default value		

Note:

- 1. The function code will restore to 0 after finishing the operation of the selected function code.
- 2. Restoring to the default value will cancel the user password, please use this function with caution.
- 3. Power off vsd for 1 min, then power back on

#### Master Reset:

GROUP 29		
29.00	40721	Password
29.02	1	Change value up then date enter
29.02	0	Change value back to original value then data enter

Note:

1. Power off vsd for 1 min, then power back on

# CONNECTION



Dry Run Protection (Probes / Flout for above ground application)





Bridge out when no probe in hole

TO PROBES / Flout

05.03=46

EXTERNAL SWITCH (DRY CONTACT) – FLOAT / PRESSURE SWITCH







Run on Auto

## AC OUTPUT CONNECTION





Connect motor wire to correct number on the AC OUTPUT PLUG

#### **<u>3PH Motors:</u>**

- 1,2,3 Connect motor
- 4 Earth

### **<u>1PH Motors (Excl Run Cap)</u>**:

- 1 & 3 Run and Start
- 2 Common
- 4 Earth

### <u>1PH Motors (with Run Cap):</u>

- 2 Neutral
- 3 Live
- 4 Earth



Do as follows after inverter encounter a fault

- 1. First, check whether there is something wrong with the keypad. If yes, contact the local INVT office
- 2. If there is nothing wrong, check function codes of P07 group, view the corresponding recorded fault parameters, and identify the actual state when the current fault occurred based on all the parameters
- 3. See the following table, check for exceptions based on the specific solutions.
- 4. Rectify the fault or seek help
- 5. After ensuring that the fault has been rectified, perform fault reset and start the inverter

Fault code	Fault type Possible cause		Solutions
OV1	Overvoltage when acceleration		<ol> <li>Check the input power.</li> <li>Check if the DEC time of the</li> </ol>
OV2	Overvoltage when deceleration	1. The input voltage is abnormal. 2. There is large energy feedback.	load is too short or the inverter starts during the rotation of the
OV3	Overvoltage when constant speed running	<ul><li>3. No brake components.</li><li>4. Braking energy is not open.</li></ul>	<ul><li>motor, or it needs to increase the energy consumption components.</li><li>3. Install the brake components.</li><li>4. Check the setting of related function codes.</li></ul>
OC1	Overcurrent when acceleration	1 The acceleration or deceleration is	<ol> <li>Increase the ACC time.</li> <li>Check the input power.</li> </ol>
OC2	Overcurrent when deceleration	too fast. 2. The voltage of the grid is too low.	3. Select the inverter with a larger power.
OC3	Overcurrent when constant speed running	<ol> <li>The power of the inverter is too low.</li> <li>The load transients or is abnormal.</li> <li>The grounding is short circuited, or the output is phase loss.</li> <li>There is strong external interference.</li> <li>The overvoltage stall protection is not open</li> </ol>	<ul> <li>4. Check if the load is short</li> <li>circuited (the grounding short</li> <li>circuited or the wire short circuited)</li> <li>or the rotation is not smooth.</li> <li>5. Check the output configuration.</li> <li>6. Check if there is strong</li> <li>interference.</li> <li>7. Check the setting of related</li> <li>function codes</li> </ul>
UV	Bus undervoltage	<ol> <li>The voltage of the power supply is too low.</li> <li>The overvoltage stall protection is not open.</li> </ol>	<ol> <li>Check the input power of the supply line.</li> <li>Check the setting of related function codes.</li> </ol>
OL1	Motor overload	<ol> <li>The voltage of the power supply is too low.</li> <li>The motor setting rated current is incorrect.</li> <li>The motor stall or load transients is too strong.</li> </ol>	<ol> <li>Check the power of the supply line.</li> <li>Reset the rated current of the motor.</li> <li>Check the load and adjust the torque lift.</li> </ol>
OL2	Inverter overload	<ol> <li>The acceleration is too fast.</li> <li>The rotating motor is reset.</li> <li>The voltage of the power supply is too low.</li> <li>The load is too heavy.</li> <li>The motor power is too small.</li> </ol>	<ol> <li>Increase the ACC time.</li> <li>Avoid the restarting after stopping.</li> <li>Check the power of the supply line.</li> <li>Select an inverter with bigger power.</li> <li>Select a proper motor.</li> </ol>

Fault code	Fault type	Possible cause	Solutions
SPI	Input phase loss	Phase loss or fluctuation of input R,S,T	<ol> <li>Check input power.</li> <li>Check installation distribution.</li> </ol>
SPO	Output phase loss	U,V,W phase loss output (or serious asymmetrical three phase of the load)	<ol> <li>Check the output distribution.</li> <li>Check the motor and cable.</li> </ol>
OH1	Rectifier overheat	1. Air duct jam or fan damage	1. Dredge the wind channel or change
OH2	IGBT overheat	<ol> <li>Ambient temperature is too high.</li> <li>The time of overload running is too long.</li> </ol>	the fan. 2. Decrease the environment temperature.
EF	External fault	SI external fault caused by actions of input terminals	Check the external device input.
CE	485 Communication error	<ol> <li>The baud rate setting is incorrect.</li> <li>Fault occurs to the communication wiring.</li> <li>The communication address is wrong.</li> <li>There is strong interference to the communication</li> </ol>	<ol> <li>Set proper baud rate.</li> <li>Check the communication connection distribution</li> <li>Set proper communication address.</li> <li>Change or replace the connection distribution or improve the anti- interference capability.</li> </ol>
ItE	Current detection fault	<ol> <li>The control panel connector is in poor contact.</li> <li>The Hall component is damaged.</li> <li>The magnifying circuit is abnormal.</li> </ol>	<ol> <li>Check the connector and rewire.</li> <li>Replace the Hall component.</li> <li>Replace the main control panel.</li> </ol>
EEP	EEPROM fault	<ol> <li>Error occurs in writing or reading control parameters.</li> <li>EEPROM is damaged.</li> </ol>	<ol> <li>Press [STOP/RST] to reset.</li> <li>Replace the main control panel.</li> </ol>
PIDE	PID feedback fault	<ol> <li>PID feedback is offline.</li> <li>The PID feedback source disappears.</li> </ol>	<ol> <li>Check the PID feedback signal line.</li> <li>Check the PID feedback source.</li> </ol>
END	Running time reached	The actual running time of the inverter is longer than the preset running time.	Ask the supplier to adjust the preset running time.
OL3	Electrical overload	The inverter will report overload pre-alarm according to the set value.	Check the load and the overload pre- alarm points.
dEu	Velocity deviation fault	The load is too heavy or stalled.	<ol> <li>Check the load and ensure it is normal. Increase the detection time.</li> <li>Check whether the control parameters are normal.</li> </ol>
STo	Maladjustment fault	<ol> <li>The control parameters of the synchronous motors not set properly.</li> <li>The autotuning parameter is not correct.</li> <li>The inverter is not connected to the motor</li> </ol>	<ol> <li>Check the load and ensure it is normal.</li> <li>Check whether the control parameter is set properly or not.</li> <li>Increase the maladjustment detection time.</li> </ol>
LL	Electronic underload fault	The inverter will report the underload pre-alarm according to the set value.	Check the load and the underload pre-alarm points.
tSF	Hydraulic probe damage	The hydraulic probe is damaged.	Replace the hydraulic probe.

Fault code	Fault type	Possible cause	Solutions
PINV	PV reverse connection fault	The PV wiring is not properly performed.	Identify the positive and negative PV terminals, and rewire.
PVOC	PV overcurrent	<ol> <li>The ACC/DEC is too fast.</li> <li>The inverter power is too low.</li> <li>The load suddenly changes or is abnormal</li> <li>The grounding is short circuited.</li> </ol>	<ol> <li>Increase the ACC/DEC time.</li> <li>Use an inverter with greater power.</li> <li>Check whether the grounding or cable connection is short circuited or whether the rotation is blocked.</li> </ol>
PVOV	PV overvoltage	The solar panel input voltage is too high, or the model is 380V but set to 220V.	<ol> <li>Reduce the serially connected solar panels.</li> <li>Check and reset the model.</li> </ol>
PVLV	PV undervoltage	<ol> <li>The power of the serially connected solar panels is too low, or it is rainy and cloudy.</li> <li>The starting current of the motor is too high.</li> </ol>	<ol> <li>Increase solar panels or test it again under normal sunlight.</li> <li>Replace the motor.</li> </ol>
A-LS	Weak light alarm	The sunlight is weak or too few solar panels are configured.	<ol> <li>The device automatically operates after the sunlight gets stronger, and no processing is needed.</li> <li>Check whether solar panels are properly configured.</li> </ol>
A-LL	Underload alarm	The water pumping tank is empty.	Check the water pumping tank. Set 05.17 lower by 10
A-tF	Water full alarm	The water storing tank is full.	If the water full alarm function is enabled, the device automatically stops after the water full alarm remains for a certain period of time, and no processing is needed. If the water full alarm function is not enabled, check whether there are terminals misconnected.
A-tL	Water empty alarm	The water pumping tank is empty.	1. If the water empty alarm function is enabled, the device automatically stops after the water empty alarm remains for a certain period of time, and no processing is needed. If the water empty alarm function is not enabled, check whether there are terminals misconnected.